COEN-4720 Embedded Systems

Lecture 1 Introduction

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1

1

Outline

- Admin
- What is an Embedded System (ES)
- Examples of embedded systems
- Embedded systems characteristics
- How to design an embedded system
- ARM Cortex-M processors

Admin

- Discussion of Syllabus
- Grading policies, attendance, labs, etc.
- •Course websites:
 - ° D2L:
 - https://d2l.mu.edu/d2l/login
 - ° Public:
 - http://deiazzer.com/coen4720/index.html

3

3

What is an Embedded System?

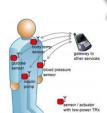
- Multiple definitions:
 - Any electronic system that uses a computer chip, but that is not a general-purpose workstation, desktop or laptop computer
 - Some combination of computer hardware and software, either fixed in capability or programmable, that is specifically designed for a particular function
 - A multi-agent system and computer system designed for specific control functions within a larger system, often with real-time computing constraints

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Embedded Systems

- Systems that are part of a larger system
 - Application-specific
 - Diverse application areas
- Tight constraints
 - Real-time, performance, power, size
 - Cost, time-to-market, reliability
- Ubiquitous
 - Far bigger market than general purpose computing (PCs, servers)
 - 98% of all processors sold















5

Where are Embedded Systems Used?

Everywhere

- ° industrial machines
- ° automobiles, trains
- ° airplanes, space vehicles
- ° medical equipment
- ° video games, cameras, MP3 players, TVs
- $^{\circ}$ cell phones
- $^{\circ}$ vending machines, household appliances, toys

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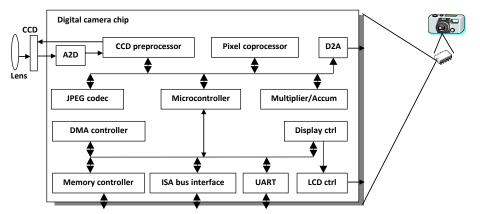
Types of Embedded Systems

- General
 - $^{\circ}\,$ similar to traditional computer systems, in a smaller package

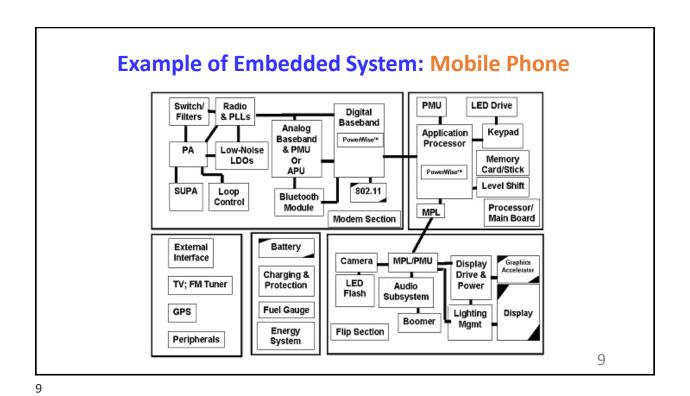
 - ° portable games
- Communications
 - ° cell phones
- Signal Processing ° video and audio
- Control
 - ° real time feedback control
 - ° automotive
 - ° aerospace
 - ° appliances

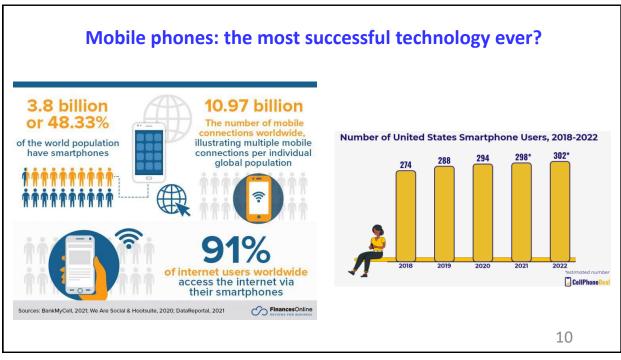
7

Example of Embedded System: Digital Camera



- Single functionality always a digital camera
- Tightly constrained low cost, low power, small, fast
- Reactive and real time only to a small extent



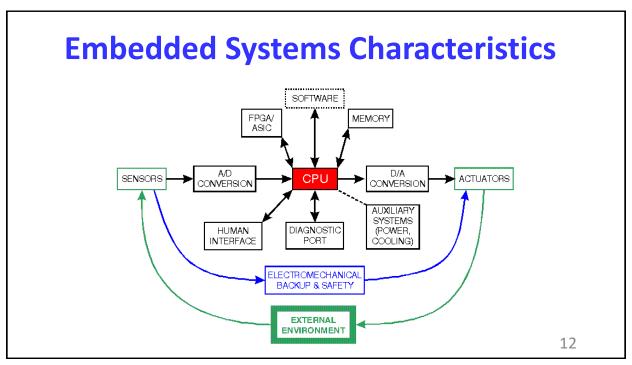


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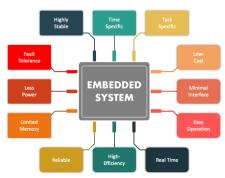
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11



Embedded Systems Characteristics

- Part of a larger system (system within system)
- Computational
- Interact (sense, manipulate, communicate) with the external world: sensors, actuators
- Reactive: at the speed of the environment
- Heterogeneity: hardware/software blocks, mixed architectures
- Networked: shared, adaptive, sensor networks (buildings environmental monitoring), smart products, wearable computing
- Flexibility: can run/implement multiple applications sequentially or concurrently concurrency
- Reprogrammability/reconfigurability: flexibility in upgrading, bug fixing, product differentiation, product customization
- Performance and constraints:
 - ° Timing (frequency, latency, throughput)
 - Real time critical, safety, reliability
 - ° Power consumption, area, temperature
 - ° Weight, size, cost (hardware & software), time to market



Source: theengineeringprojects.com

13

13

Key Trends

- Difficult to design
 - ° Planes still crash
 - ° Car recalls...
- Getting even harder to design:
 - ° Increasing computation demands, increasing complexity
 - e.g., multimedia processing in set-top boxes, HDTV
 - ° Increasingly networked and distributed
 - ° Increasing need for flexibility
 - programmable & customizable
 - time-to-market under ever changing standards
 - ° Reaching physical limits of technology scaling
 - Power walls (and dark silicon)
 - Efficiency/optimality vs. flexibility/generality

Key Trends

- Technological advances
 - ° Higher integration: more blocks on the same chip
 - ° Multi-Processor System-On-Chip (MPSoC)
- Embedded systems evolve toward
 - System-on-Chip (SoC)
 - ° Cyber Physical Systems (CPS)
- IP reuse, platform based design, NoC vs. Bus
- HW-SW co-design
- Diversity in design methodologies, platform dependent, lack of standards, quality risks, customer confusion
- Systems are designed and built as "systems of systems"
- Opportunity and need for specialization
 - ° Heterogeneous multi-core / Asynchronous CMP
 - ° GP-GPUs

15

15

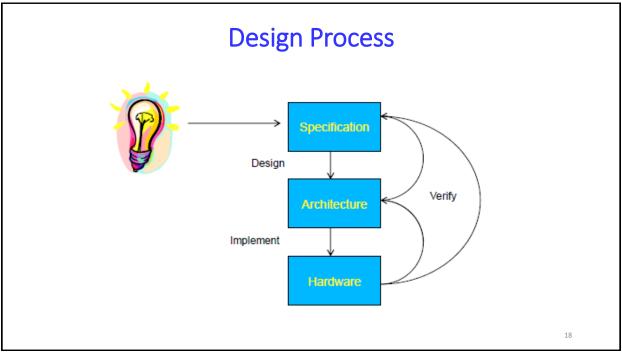
SoC and IoT Market Size Global IoT revenue by technology segment (\$bn), 2018–2023 GlobalData. Global System-On- Chip Market Transparency By Region, 2018 (US\$ Bn) Software and services Connectivity Devices CAGR 11.0% (2018-2026) Asia Pacific 31 24 North America 39.7 Europe South America Source: GlobalData, Technology Intelligence Centre Source: Transparency Market Research Analysis, 2018 16

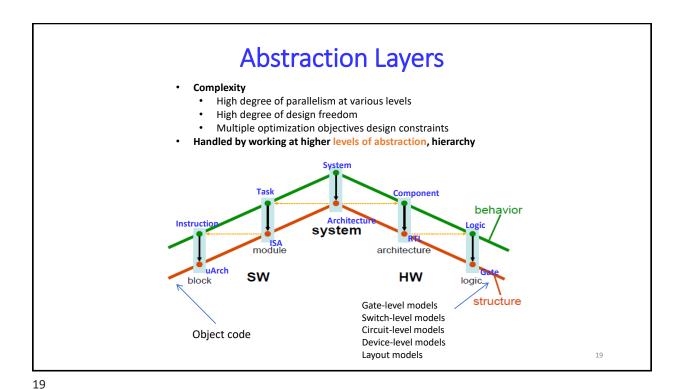
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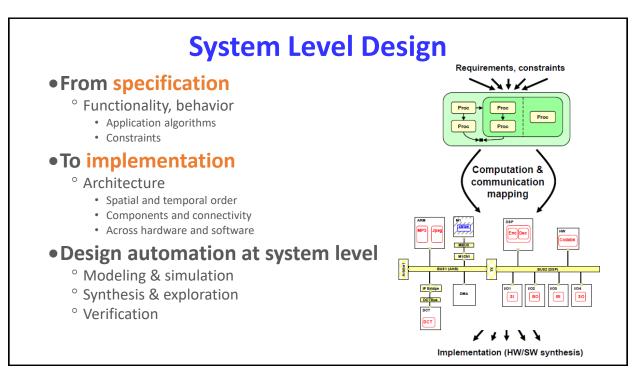
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17

17







1) System Specification

Capture requirements (what)

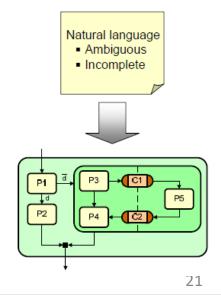
- ° Functional
 - Free of any implementation details
- ° Non-functional
 - Constraints

Formal representation

- ° Models of computation
 - Objects & composition rules
 - · Concurrency & time
 - Computation & communication
- ° Executable
 - Semantics

Application development

- Precise description of desired system behavior
 - · Complete and unambiguous



21

2) System Architecture

Architecture definition

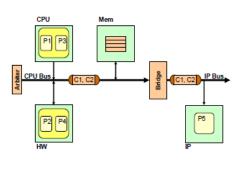
- ° Processing elements (PEs)
 - Processors, memories, FPGAs, DSPs
- ° Communication elements
 - · Busses, Networks-on-Chip (NoCs), transducers, bus bridges

Virtual platform prototyping

- ° PE simulation (functional, full-system) for computation
- Event-driven simulation, transaction-level modeling (TLM) for communication

Design space exploration and system optimization

- Partitioning, mapping (allocation + binding), scheduling
- Estimation: Synthesis based on abstraction only makes sense if there are powerful estimation methods available:
 - Estimate properties of the next layer(s) of abstraction
 - Design decisions are based on these estimated properties



3) System Implementation

Hardware

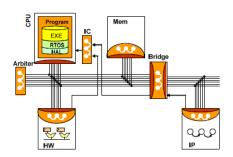
- Microarchitecture models
- ° Register-transfer level (RTL)
- ° Layouts

Software binaries

- ° Application object code
- ° Real-time operating system (RTOS)
- ° Hardware abstraction layer (HAL)

System netlist

- ° Pins and wires
- ° Arbiters, muxes, interrupt controllers (ICs), etc.
- ° Bus protocol state machines

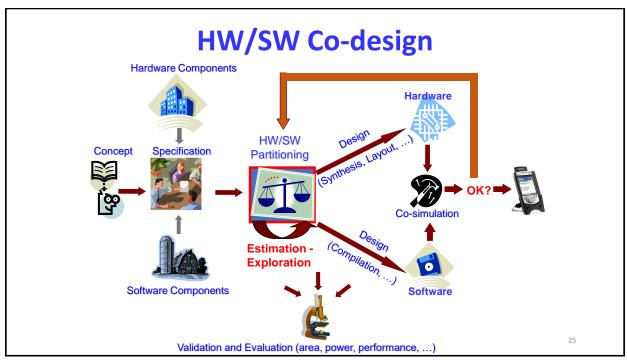


23

23

Hardware vs. Software Modules

- Significant part of the problem is deciding which parts should be in software on programmable processors, and which in specialized hardware
- Hardware = functionality implemented via a custom architecture (datapath + FSM)
- **Software** = functionality implemented in software on a programmable processor
- Key differences:
 - Multiplexing
 - · software modules multiplexed with others on a processor
 - hardware modules are typically mapped individually on dedicated hardware
 - Concurrency
 - processors usually have one "thread of control"
 - · dedicated hardware often has concurrent datapaths



25

HW/SW Co-design

- HW/SW Co-design means the design of a special-purpose system composed of a few application-specific ICs that cooperate with software procedures on general-purpose processors (1994)
- HW/SW Co-design means meeting system-level objectives by exploiting the synergism of hardware and software through their concurrent design (1997)
- HW/SW Co-design tries to increase the predictability of embedded system design by providing analysis methods that tell designers if a system meets its performance, power, and size goals and synthesis methods that let designers rapidly evaluate many potential design methodologies (2003)
- It moved from an emerging discipline (early '90s) to a mainstream technology (today)

System Level Design Flow (Methodology)

- Past and present:
 - Ad hoc approaches based on earlier experience with similar products, and on manual design
 - HW/SW partitioning decided at the beginning, and then designs proceed separately
- Present and future:
 - From HW/SW co-design to HW/SW co-synthesis
 - Design automation (CAD) tools: very challenging

27

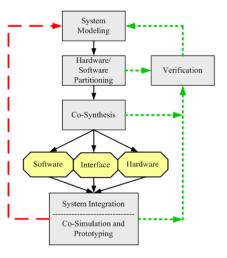
27

From HW/SW Co-design to HW/SW Co-synthesis

- Early approaches: HW/SW partitioning would be done first and then HW/SW blocks would be synthesized separately
- Ideally, system synthesis would do HW/SW partitioning, mapping, and scheduling in a unified fashion – very difficult
- Design space exploration (estimation and refinement)
 would also be done in a unified fashion; by working at the
 same time with both HW and SW modules → co-synthesis
- Key: communication models

HW/SW Co-synthesis

- Co-synthesis: Synthesize the software, hardware and interface implementation in a unified fashion.
- Done concurrently with as much interaction as possible between the three implementations.



29

29

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Why study the ARM architecture (Cortex-M0+ in particular)?

- Very popular in industry
- Lots of manufacturers design MCUs based off ARM processors
 - ° What differentiates these products? Peripherals (aka devices)!

















31

31

Summary

- Embedded systems are everywhere!
- •Big picture:
 - $^{\circ}$ Embedded systems ightarrow SoC, IoT
 - $^{\circ}$ Abstraction layers and system-level design ightarrow handle complexity
 - ° Key challenge: optimization of design metrics, which compete with one another
 - ° Unified view of hardware & software is necessary
- •Focus of this course:
 - ° Rather simple embedded systems ARM Cortex-M0+ based MCU

Embedded Systems and You

- As engineers, it is very likely that you will:
 - ° Design microprocessors and other digital circuits (e.g., ASICs, FPGAs, etc.) to be used in embedded applications
 - ° Develop algorithms (control, signal processing, etc.) that will be implemented on embedded microprocessors
 - ° Develop software (e.g., design automation CAD tools, RTOS, apps, etc.) for the embedded market
 - ° Work in application fields that involve an embedded microprocessor
 - Design sensors/actuators (e.g., MEMS devices) that may be used in embedded systems
 - ° Design and implement complete systems that contain embedded systems
- It is certain that you encounter embedded systems in all aspects of your daily life!

33

Skills Needed

- An embedded system application involves a diverse set of skills that extend across traditional disciplinary boundaries, including
 - computer hardware
 - software
 - algorithms
 - interface electronics
 - application domain
- Make engineering tradeoffs that extend across these boundaries